

* n -dimensional (smooth) submanifolds of \mathbb{R}^{n+k}

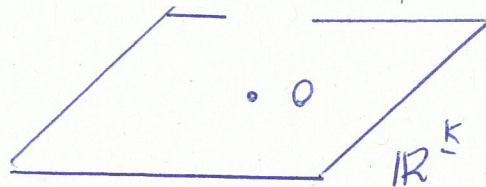
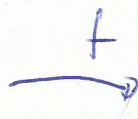
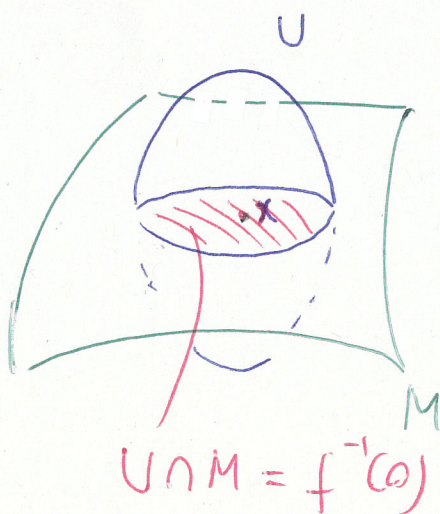
Definition: $M \subset \mathbb{R}^{n+k}$ is said to be a smooth n -dimensional submanifold of \mathbb{R}^{n+k}

if $\forall x \in M, \exists U \ni x$ in \mathbb{R}^{n+k}
neighbourhood

and a submersion $f: U \rightarrow \mathbb{R}^k$
(smooth)

such that $U \cap M = f^{-1}(0)$

level set of f pertaining
to $0 \in \mathbb{R}^k$
(0-level set)



By Dini's Theorem, $f^{-1}(0)$
will be also locally described
by injective immersions
(locally embeddings)

DIFFERENTIAL GEOMETRY
AND TOPOLOGY

V2

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Lecture III

REVIEW OF CALCULUS IN
SEVERAL VARIABLES III

III-1

Given $x_0 \in f^{-1}(0)$,

$$\underbrace{\text{ker } f_*|_{x_0}}_{n\text{-dimensional}} \leq \underbrace{\mathbb{R}^{n+k}}_{\text{subspace}}$$

is called the **tangent space to M at x_0**

In fact, a moment's reflection shows that $\text{ker } f_*|_{x_0}$ (an n -dimensional subspace of \mathbb{R}^{n+k}) consists precisely of the velocity vectors of curves issuing from x_0 and entirely lying on $U \cap M = f^{-1}(0)$ for sufficiently small t .

Indeed, for $x_0 \in f^{-1}(0)$ ($f(x_0) = 0$), let $\alpha = \alpha(t)$, $\alpha(0) = x_0$, $t \in I$ (an interval containing 0) $\dot{\alpha}(0) \equiv \dot{\xi} \in \mathbb{R}^{n+k}$ be a smooth curve lying in $f^{-1}(0)$: the function $F = F(t) := f(\alpha(t)) \equiv 0 \quad \forall t \in I$.

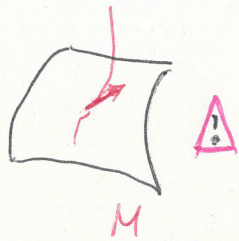
Differentiation with respect to t yields

$$\frac{\partial f}{\partial x^i} \dot{x}^i \equiv 0 \quad \text{and, in particular, at } t=0$$

$$\boxed{f_*|_{x_0} \dot{\xi} = 0}$$

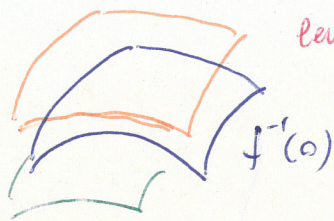
$$\mathbb{R} \boxed{f_*|_{x_0}} \begin{matrix} \mathbb{R}^{n+k} \\ \downarrow \xi \end{matrix} = \begin{matrix} \mathbb{R} \\ 0 \end{matrix}$$

conversely, as a consequence of Darb's theory,
 any vector in $\ker f_*|_{x_0}$ can be viewed as the
 velocity vector of a curve stemming from x_0
 and entirely contained in $f^{-1}(c)$



this may
 happen, in
 principle

idea: possibly clearer in the sequel

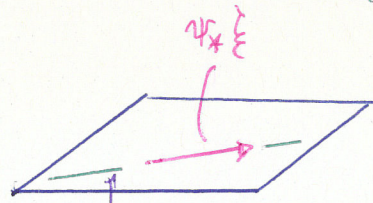


level sets of f

ψ

diffeomorphism

slices



via ψ^{-1}

take a straight
 line γ

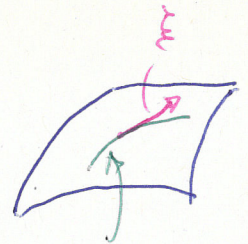


image of γ
 $(\psi^{-1} \circ \gamma)$

this is the required curve

Examples

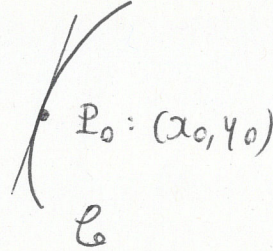
1. curves in \mathbb{R}^2 (defined implicitly)

$$f \in C^0(\mathbb{R}^2)$$

$$\mathcal{C}: f(x, y) = 0$$

0-level set of f

Let:



$$(\diamond) \quad \frac{\partial f}{\partial y}(P_0) \neq 0$$

Then (Dini), there exists, locally $y = y(x)$ (C^0)
 $y(x_0) = y_0$, $f(x, y(x)) \equiv 0$ $x \in I$ interval containing x_0

Condition (\diamond) ensures that f is submersive at P_0 :
(and locally as well)

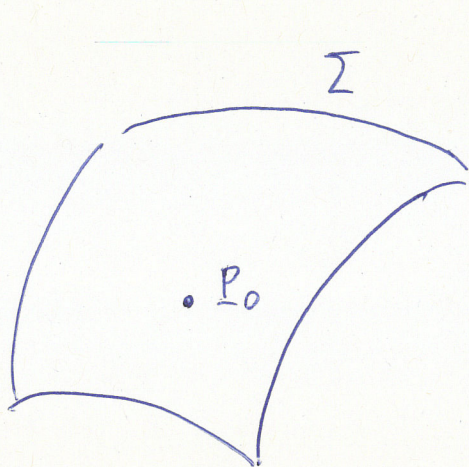
$$f_*|_{P_0} = (f'_x, f'_y)|_{x_0} \quad (\Rightarrow \text{rk}(f_*|_{P_0}) = 1 = \max)$$

The tangent space to \mathcal{C} at P_0 is precisely the (direction of the) tangent line to \mathcal{C} at P_0 : the equation of the latter is, indeed

$$(\diamond\diamond) \quad f'_x(x-x_0) + f'_y(y-y_0) = 0 \quad (f'_x, f'_y) \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} = 0$$

$$\xi = \begin{pmatrix} \xi_1 \\ \xi_2 \end{pmatrix} \text{ satisfies } (\diamond\diamond) \Leftrightarrow \xi \in \text{Ker } f_*|_{P_0}$$

2. Surfaces in \mathbb{R}^3 (defined implicitly)



$\Sigma: f(x, y, z) = 0 \quad f \in C^\infty(\mathbb{R}^3)$
 $P_0: (x_0, y_0, z_0)$

(◇) $\frac{\partial f}{\partial z}(P_0) \neq 0 \Rightarrow$
 D_{mi}

$z = z(x, y) \quad z_0 = z(x_0, y_0)$

$f(x, y, z(x, y)) \equiv 0 \quad \text{for } (x, y) \in \mathcal{U}$
 \cap
 (x_0, y_0)

Tangent plane to Σ at P_0 :

(◇◇) $f'_x(x-x_0) + f'_y(y-y_0) + f'_z(z-z_0) = 0$
 $\xi_1 \quad \xi_2 \quad \neq 0 \quad \xi_3$

Condition (◇) tells us that f is submersive at P_0
 (and locally as well)

$f_*|_{P_0} = (f'_x, f'_y, f'_z) \quad (\text{rk}(f_*|_{P_0}) = 1 = \max)$
 $\neq 0$

(◇◇) is tantamount to the condition

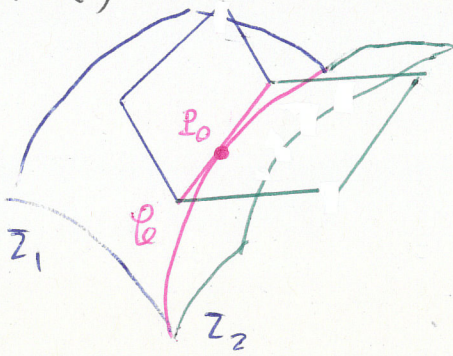
$\xi \in \ker(f_*|_{P_0})$

$(f'_x, f'_y, f'_z) \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} = 0$

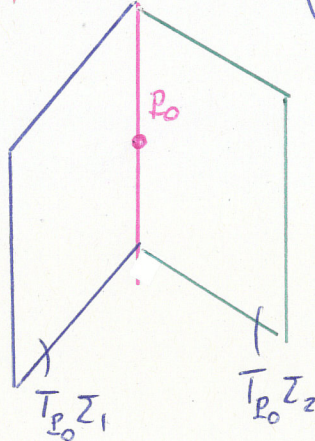
3. Curves in \mathbb{R}^3 defined implicitly

$$\mathcal{C} = \begin{cases} f(x, y, z) = 0 & \Sigma_1 \\ g(x, y, z) = 0 & \Sigma_2 \end{cases} \quad F: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$F^{-1}(0)$



$P_0: (x_0, y_0, z_0)$



$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} f(x, y, z) \\ g(x, y, z) \end{pmatrix}$$

surjectivity of $F_*|_{P_0}$ can be

imposed by requiring e.g.

$$\left. \begin{aligned} \frac{\partial(f, g)}{\partial(x, y, z)}(P_0) \neq 0 \end{aligned} \right\}$$

\Downarrow Dini locally around α_0 :

$$\mathcal{C}: \begin{cases} x = x \\ y = y(x) \\ z = z(x) \end{cases}$$

$$\begin{aligned} y(\alpha_0) &= y_0 \\ z(\alpha_0) &= z_0 \end{aligned}$$

$$\begin{cases} f(x, y(x), z(x)) = 0 \\ g(x, y(x), z(x)) = 0 \end{cases}$$

Tangent line to \mathcal{C} at P_0

$$T_{P_0}\Sigma_1 \ni \left\{ \begin{aligned} f'_x(x-x_0) + f'_y(y-y_0) + f'_z(z-z_0) &= 0 \end{aligned} \right.$$

$$T_{P_0}\Sigma_2 \ni \left\{ \begin{aligned} g'_x(x-x_0) + g'_y(y-y_0) + g'_z(z-z_0) &= 0 \end{aligned} \right.$$

intersecting transversally

rewrite lines as follows

$$\begin{pmatrix} f'_x & f'_y & f'_z \\ g'_x & g'_y & g'_z \end{pmatrix} \begin{pmatrix} \xi_1 \\ \xi_2 \\ \xi_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \iff \xi \in \ker F_*|_{P_0}$$