

Lectures on **DIFFERENTIAL GEOMETRY AND TOPOLOGY V2**

Let $K = \mathbb{R}$, and let $(V, \langle \cdot, \cdot \rangle)$ be a Euclidean vector space, i.e. $\langle \cdot, \cdot \rangle$ is an inner product (Scalar product)

[work in finite dimensions]

$$\langle \cdot, \cdot \rangle : V \times V \longrightarrow \mathbb{R}$$

is a function fulfilling the following properties

1. bilinearity

(linearity in both arguments)

$$\langle \alpha v_1 + \beta v_2, w \rangle = \alpha \langle v_1, w \rangle + \beta \langle v_2, w \rangle \text{ etc}$$

2. Symmetry

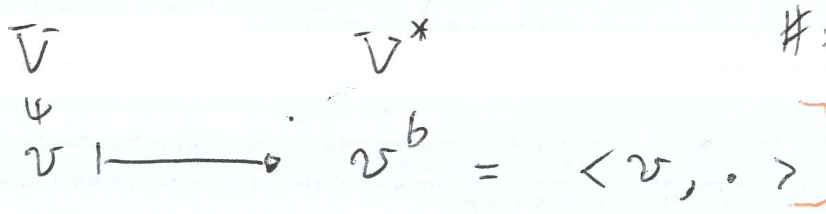
$$\langle v, w \rangle = \langle w, v \rangle \quad \forall v, w \in V$$

3. positive definiteness

$$\langle v, v \rangle \geq 0 \quad \text{and equality holds if and only if } v = \underline{0}$$

$\langle \cdot, \cdot \rangle$ induces specific isomorphisms (musical isomorphisms) between V and V^*

$A = LA$
 $A^\# = B^b \quad LA^\# = S_1^b$
 $B = S_1 \dots$
 $C^\# = D^b$



b : flat
 $\#$: Sharp
 (inverse to each other)



inner product against a fixed vector

b is clearly injective

(indeed $v^b = 0$ iff $\langle v, w \rangle = 0 \quad \forall w \in V$

\Rightarrow in particular $\langle v, v \rangle = 0 \Rightarrow v = 0$
(positive definiteness))

hence surjective ($N+R$), and its inverse is called
 $\#$. This is also expressed by means of the

Riesz representation theorem, in the following guise:

* Let $(V, \langle \cdot, \cdot \rangle)$ be a Euclidean vector space,
 $\dim_{\mathbb{R}} V = n$. Let $l \in V^*$. Then, $\exists! u \in V$
such that, $\forall v \in V$, one has

$$l(v) = \langle u, v \rangle$$

[conversely, as we have already observed, $\forall u \in V$, the
position $l_u(v) := \langle u, v \rangle$ defines a linear functional]

Proof. Let (e_1, \dots, e_n) be an orthonormal basis of V ,
i.e. $\langle e_i, e_j \rangle = \delta_{ij} \quad i, j = 1, \dots, n$. [Such a basis can
be manufactured from any basis via the Gram-Schmidt
procedure]. Then $v = \sum \alpha_i e_i$ (α_i uniquely
determined)

Thus $l(v) = \sum_{i=1}^n \alpha_i l(e_i)$. Set $u_i = l(e_i)$

and $u = \sum_{i=1}^n u_i e_i$. Then u is the sought-for
vector

Indeed: $\langle u, v \rangle = \langle \sum_i u_i e_i, \sum_j v_j e_j \rangle$
 $= \sum_{i,j} u_i v_j \underbrace{\langle e_i, e_j \rangle}_{\delta_{ij}} = \sum_{i=1}^n u_i v_i = l(v)$ \square

Notice that

we employed bases...

We wish to be more explicit

Concretely, $\langle \cdot, \cdot \rangle$ can be represented, given any basis $\langle e_1, \dots, e_n \rangle$, via a matrix $\mathcal{L} = (g_{ij} = \langle e_i, e_j \rangle)$.

In fact if $v = \sum v^i e_i$ $w = \sum w^j e_j$

(compactly: $v = v^i e_i$
 $w = w^j e_j$ Einstein's convention)

notice this $\sum_{i,j}$

$$\langle v, w \rangle = \sum_{i,j} v^i w^j \langle e_i, e_j \rangle = \sum_{i,j} g_{ij} v^i w^j$$

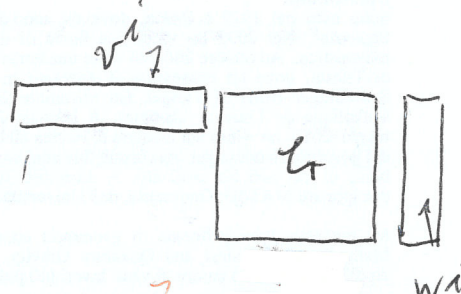
compactly: $g_{ij} v^i w^j$

with \mathcal{L} symmetric and positive definite. sum over i & j

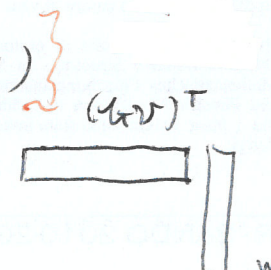
Conversely, given a basis on V and a symmetric, positive definite \mathcal{L} , one defines an inner product via the above formula. The latter, in turn, can be rewritten as follows:

$$\langle v, w \rangle = v^T \cdot \mathcal{L} \cdot w$$

(matrix products...)



But $v^T \mathcal{L} w =$

$$v^T \mathcal{L}^T w = (\mathcal{L} v)^T w = l_{\mathcal{L}v}(w)$$


where l_{GV} is the linear functional

corresponding to the row vector $(GV)^T$

One sets $v_i := g_{ij} v^j$ Einstein's summation convention

so $\langle v, w \rangle = v_i w^i$

this explains the musical terminology

Therefore $\boxed{b} : (v^i) \mapsto (v_i)$

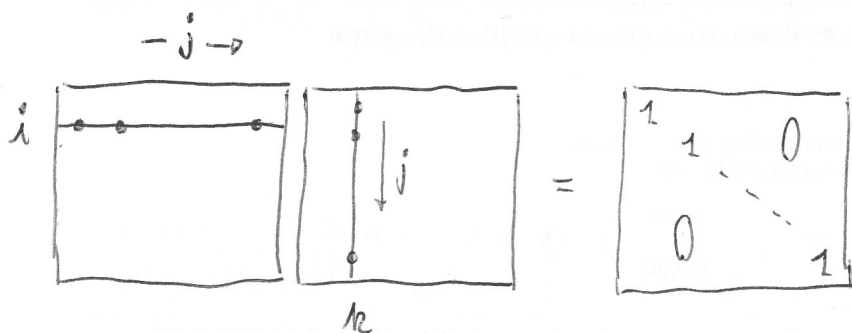
i.e. it lowers indices.

let us visualise $\# = b^{-1}$: this will involve the inverse g^{-1} of g set $g^{-1} = (g^{ij})$

then by definition

$$g^{ij} g_{jk} = \delta_{ik} = \delta_{ik}$$

again sum over j



$$g^{-1} g = g g^{-1} = I$$

Start from l , i.e. from a row vector $(v_i) = v^T$.

One finds, successively:

components of l with respect to the dual bases $(e_1^* \dots e_n^*)$
 $(e_1 \dots e_n)$

$$((A^{-1})^T)^T = (A^T)^T \equiv A^{-T}$$

$$\begin{aligned} l(w) &= v^T w = v^T g^{-1} g w = v^T g^{-T} g w \\ &= (g^{-1} v)^T g w \equiv \langle v^\#, w \rangle \end{aligned}$$

that is: $v^\# = g^{-1} v$

in components: $v^i = g^{ij} v_j$

namely,
indices are raised

Summarizing:

$$\begin{aligned} v_i &= g_{ij} v^j & b \\ v^i &= g^{ij} v_j & \# \end{aligned}$$

$$v_i w^i = g_{ij} v^j w^i = g_{ij} w^i v^j = \dots = v^i w_i$$

observe

Example

Let $(\mathbb{R}^2, \langle, \rangle)$, with \langle, \rangle represented, w.r. to the canonical basis, by

$$g = (g_{ij}) = \begin{pmatrix} 2 & 0 \\ 0 & 4 \end{pmatrix}$$

Let $v = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$. Find v^b .

One has

$$v^b = (g v)^T$$

$$= \left[\begin{pmatrix} 2 & 0 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right]^T = \begin{pmatrix} 2 \\ 4 \end{pmatrix}^T = (2, 4)$$

Now, given $\omega = (2, 4)$, find $\omega^\#$.

We have

$$\omega^\# = \overset{\text{caveat}}{g^{-1}} \omega^T = \begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{4} \end{pmatrix} \begin{pmatrix} 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

as expected, since $b = \#^{-1}$, $\# = b^{-1}$.

recall:

$$v_i = g_{ij} v^j$$

$$v^i = g^{ij} v_j$$