

Lectures on

DIFFERENTIAL GEOMETRY AND TOPOLOGY

V2

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MULTILINEAR ALGEBRA

Lecture X

\*  $\mathbb{R}$ -forms (continued)

$\mathbb{R}$ -forms (continued)  
products of  $\mathbb{R}$ -1 forms  
Further examples  
Linear algebraic  
algebra  
Grassmann algebra

If  $\omega_1, \omega_2, \dots, \omega_k \in \Delta^k(V^*)$ , one finds  
again  $\dim V = n \dots$

$(\omega_1 \wedge \omega_2 \wedge \dots \wedge \omega_k)(v_1, v_2, \dots, v_k) =$   
 $\leftarrow v \text{ fixed} \rightarrow$

determinant

$$\begin{vmatrix} \omega_1(v_1) & \dots & \omega_k(v_1) \\ \vdots & & \vdots \\ \omega_1(v_k) & \dots & \omega_k(v_k) \end{vmatrix}$$

$\updownarrow$   $v$  fixed

which represents the volume of a suitable hyperparallelepiped in  $\mathbb{R}^k$

(set  $\mathbb{R}^n \ni \xi \mapsto (\omega_1(\xi), \dots, \omega_k(\xi)) \in \mathbb{R}^k$   
(row notation))



Consider, in particular, the  $k$ -forms

$$e_{i_1}^* \wedge e_{i_2}^* \wedge \dots \wedge e_{i_k}^*$$

$$i_1 < i_2 < \dots < i_k$$

They yield a basis of  $\Lambda^k(V^*)$ :

recall  $e_i^*(e_j) = \delta_{ij}$

one easily checks that

$$(e_{i_1}^* \wedge \dots \wedge e_{i_k}^*)(e_{j_1}, e_{j_2}, \dots, e_{j_k}) =$$

$$= \begin{cases} \pm 1 & \text{if } \{i_1, \dots, i_k\} = \{j_1, \dots, j_k\} \\ & \text{(sign according to parity} \\ & \text{of the corresponding} \\ & \text{permutation)} \\ 0 & \text{otherwise} \end{cases}$$

and this implies

$$e_I^* = e_{i_1}^* \wedge \dots \wedge e_{i_k}^*$$

defined  
previously

## \* Pull-back of R-forms

Given  $T \in \text{Hom}(V, W) \cong W \otimes V^*$

and  $\omega \in \Delta^k(W^*)$ , the "pulled-back"

form  $T^*\omega \in \Delta^k(V^*)$  (pull-back of  $\omega$ )

is defined as follows:

$$\boxed{(T^*\omega)(v_1, \dots, v_k) := \omega(\overset{W}{\downarrow} T v_1, \dots, \overset{W}{\downarrow} T v_k)} \quad \boxed{\Delta^k(V)} \quad \boxed{\Delta^k(W^*)}$$

$\downarrow$   
 $T^* \omega \leftarrow \omega$   
 $T: V \rightarrow W$

It is immediately checked that, given homomorphisms

$$U \xrightarrow{S} V \xrightarrow{T} W, \quad \left\{ (T \circ S)^* \omega = S^* T^* \omega \right\}$$

$\uparrow$   
 $\Delta^k(W^*)$

$\nwarrow$  notice the reverse order

$$\begin{aligned} & \left\{ (T \circ S)^* \omega (v_1, \dots, v_k) = \omega(T S v_1, \dots, T S v_k) \right. \\ & = \omega(T(S v_1), \dots, T(S v_k)) = (T^* \omega)(S v_1, \dots, S v_k) \\ & = S^*(T^* \omega)(v_1, \dots, v_k) = ((S^* T^*) \omega)(v_1, \dots, v_k) \left. \right\} \end{aligned}$$

\* In  $\mathbb{R}^3$  let Further examples

$$\omega_a^1 = \sum_{i=1}^3 a_i e_i^*$$

$$\omega_b^1 = \sum_{i=1}^3 b_i e_i^*$$

$\underline{a} = (a_1, a_2, a_3)$   
 $\underline{b} = (b_1, b_2, b_3)$

Compute  $\omega_a^1 \wedge \omega_b^1$ . One gets

$$\omega_a^1 \wedge \omega_b^1 = \sum_{i,j} a_i b_j e_i^* \wedge e_j^* = \dots =$$

$$= (a_1 b_2 - a_2 b_1) e_1^* \wedge e_2^* + (a_2 b_3 - a_3 b_2) e_2^* \wedge e_3^* + (a_3 b_1 - a_1 b_3) e_3^* \wedge e_1^*$$

$(\underline{a} \times \underline{b}) \times \underline{c} \neq \underline{a} \times (\underline{b} \times \underline{c})$   
indeed  $\underline{a} = \underline{i} = \underline{b}$   
 $\underline{c} = \underline{j}$   
 $\underline{0} \neq \underline{i} \times (\underline{i} \times \underline{j})$   
 $= \underline{i} \times \underline{k} = -\underline{j}$   
 $\times$  fulfils the Jacobi identity  
 $\underline{a} \times (\underline{b} \times \underline{c}) + \text{cyclic} = \dots = \underline{0}$

components of  $\underline{a} \times \underline{b}$

flux 2-form (different notation)

Now let  $\omega_c^2(v_1, v_2) := \langle c, v_1 \times v_2 \rangle = \det \begin{pmatrix} c_1 & v_1^1 & v_2^1 \\ c_2 & v_1^2 & v_2^2 \\ c_3 & v_1^3 & v_2^3 \end{pmatrix}$

one easily checks that

$$\omega_c^2 = c_1 e_2^* \wedge e_3^* + c_2 e_3^* \wedge e_1^* + c_3 e_1^* \wedge e_2^*$$

Indeed  $\text{rot.s.}(e_1, e_2) = \dots = c_3$

and  $\omega_c^2(e_1, e_2) = \det(c, e_1, e_2) = \begin{vmatrix} c_1 & 1 & 0 \\ c_2 & 0 & 1 \\ c_3 & 0 & 0 \end{vmatrix}$

etc.

Therefore  $\omega_a^1 \wedge \omega_b^1 = \omega_c^2$ ,  $\underline{c} = \underline{a} \times \underline{b}$

= Laplace  $c_3 = \dots = 3$

$\Rightarrow \wedge$ , with a grain of salt (a metric is involved!)

can be viewed as a generalization of  $\times$  But beware:  $\wedge$  is associative,  $\times$  is not (see box)

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# \* A linear-algebraic intermezzo

\* Direct sums Given vector spaces  $U$  and  $W$  over the same field  $K$ , their direct sum

$U \oplus W$  is defined as follows:

$$U \oplus W = \{ (u, w) \mid u \in U, w \in W \}$$

with operations

$$(u_1, w_1) + (u_2, w_2) := (u_1 + u_2, w_1 + w_2)$$

↑
↑
↑  
 to be defined                      in  $U$                       in  $W$

$$\alpha \cdot (u, w) := (\alpha u, \alpha w)$$

↑
↑
↑  
 to be defined                      in  $U$                       in  $W$

Notice that

$$U \cong \{ (u, 0) \}_{u \in U} \leq U \oplus W$$

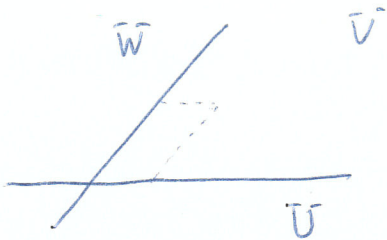
$$W \cong \{ (0, w) \}_{w \in W} \leq U \oplus W$$

(i.e.  $U$  and  $W$  are naturally realized as vector subspaces of  $U \oplus W$ )

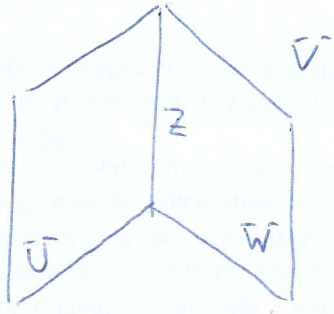
Now, given  $V$  and  $U \leq V, W \leq V$ ,  $V$  is the sum of  $U$  and  $W$ , notation  $V = U + W$ , if any  $v \in V$  can be written as  $v = u + w$  for some  $u \in U, w \in W$

If  $u$  and  $w$  are unique (and this is equivalent to  $U \cap W = \{0\}$ ), then  $U$  and  $W$  are said to be in direct sum, and one writes  $V = U \oplus W$

In general, recall Grassmann's formula  $\dim(U+W) + \dim(U \cap W) = \dim U + \dim W$



here  $V = U \oplus \bar{W}$



$Z = U \cap \bar{W} (\leq V)$   
 one has  $V = U + \bar{W}$   
 but the sum is **not** direct

★ Quotient spaces

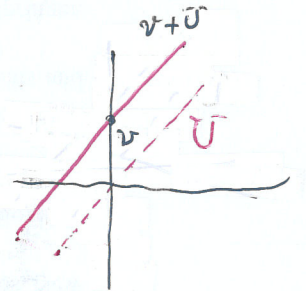
(fundamental for the sequel:  
 homology & cohomology theories)

Let  $U \leq V$ . Define the quotient vector space

$$V/U = \{ [v] := v + U \}$$

quotient of abelian groups, ( $U$  is normal in  $V$ )

linear varieties, i.e. affine subspaces of  $V$  of "direction", or "position"  $U$



structured as follows:

$$[v_1] + [v_2] := [v_1 + v_2]$$

abelian group structure with respect to +  
 to be defined  $\cdot [v] = [d \cdot v]$  (in  $V$ )

one checks that + and  $\cdot$  are well-defined, i.e. independent of the choice of a vector in its class. One also has

$V/U \cong \bar{W}$ ,  $\bar{W}$  any **direct complement** of  $U$  in  $V$   
 (i.e.  $\bar{W}$  such that  $U \oplus \bar{W} = V$ )



# \* Exterior (or Grassmann) algebra

$\dim V = n$

Let

$$\Lambda(V^*) = \bigoplus_{k=0}^n \Lambda^k(V^*)$$

$\Lambda$  (with three vertical lines above it)

$\xrightarrow{\Lambda^k}$

$\nwarrow$   $k=0$   $\nearrow$   $k$ -forms

$\nwarrow$  direct sum

(it is a vector space)

Extend  $\Lambda$  by distributivity, one has a quadruple  $(\Lambda, +, \cdot, 1)$  [  $\Lambda$  is structured via  $+ , \cdot , 1$  ]

$\uparrow$  vector space operations  $\nwarrow$  exterior product

Called exterior, or Grassmann algebra (over  $V^*$ ); its elements are called forms on  $V$ , elements in  $\Lambda^k$  are  $k$ -forms (forms of degree  $k$ )

One easily finds that

$$\dim \Lambda(V^*) = 2^n$$

$$\left( \sum_{k=0}^n \binom{n}{k} = 2^n, \text{ this immediately following from } (a+b)^n = \sum_{k=0}^n \binom{n}{k} a^k b^{n-k} \right.$$

upon setting  $a=b=1$ ).