

★ Examples

1. The sphere

$$S^2 = \{ (x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1 \}$$

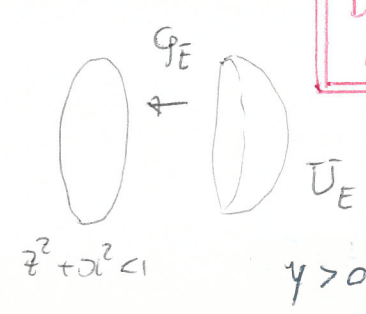
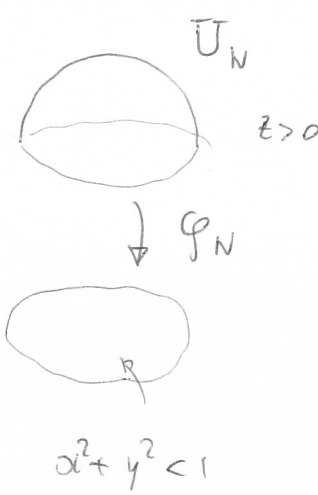
equipped with the relative topology (inherited from the standard one in \mathbb{R}^3).

Lectures on
**DIFFERENTIAL GEOMETRY
AND TOPOLOGY**

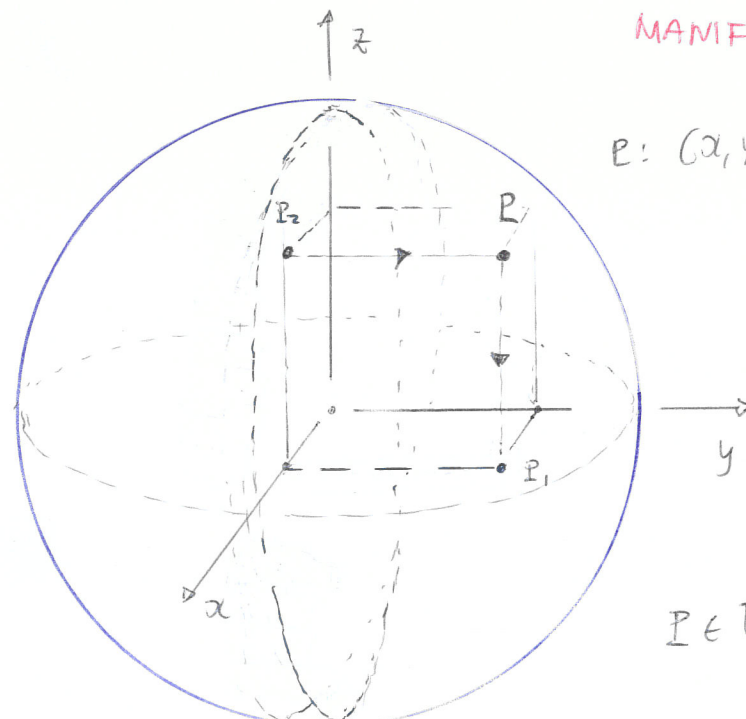
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Lecture **XV**

EXAMPLES OF
DIFFERENTIABLE
MANIFOLDS



compass-card
↑ bussola



$$P: (x, y, z)$$

$$P \in U_N \cap U_E$$



$$y = \sqrt{1 - x^2 - z^2}$$

compass:
Compasses
a punte fisse:
dividers

$$(z, x) \xrightarrow{\varphi_E^{-1}} (x, y, z)$$

$$(x, y, z) \xrightarrow{\varphi_N} (x, y)$$

$$(z, x) \xrightarrow{\varphi_N \circ \varphi_E^{-1}} (x, \sqrt{1 - x^2 - z^2})$$

\cap
 $\varphi_N(U_N) = \{ x^2 + y^2 < 1 \}$

★ $\varphi_N \circ \varphi_E^{-1}$
is smooth, with
smooth inverse

2.

A "non-example" : $x^2 + y^2 - z^2 = 0$

(cone in \mathbb{R}^3 , endowed with relative topology)

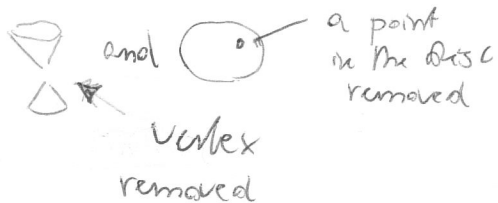


This is not a smooth manifold, and not even a topological manifold : V does not possess a neighbourhood

homeomorphic to an open disc !

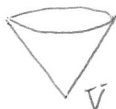


Why? Were it, then



would be homeomorphic, but this is false (the latter space is connected, the former is not)

2'



is a topological manifold (C^0)

$$x^2 + y^2 - z^2 = 0$$

$$z \geq 0$$

2''



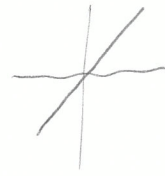
is a smooth manifold (and a ^{smooth} submanifold of \mathbb{R}^3 as well, as we have already seen)

3. A remark on the concept of differentiable structure

$$M_1 = (\mathbb{R}, t) \quad \varphi_1(t) = t$$

↑
atlas

consisting of a single chart



$$M_2 = (\mathbb{R}, t^3) \quad \varphi_2(t) = t^3$$



* The two atlases are not compatible (upon requiring $k > 0$)
degree of differentiability

$$\varphi_2^{-1} \varphi_1 : t \xrightarrow{\varphi_1^{-1}} t \xrightarrow{\varphi_2} t^3 \quad \text{is smooth}$$

$$\varphi_1^{-1} \varphi_2 : t \xrightarrow{\varphi_2^{-1}} t^{\frac{1}{3}} \xrightarrow{\varphi_1} t^{\frac{1}{3}} \quad \text{is not smooth (nor } C^k \text{ for } k \geq 1)$$



Therefore one has \mathbb{R} equipped with different differentiable structures (they are however equivalent

in a suitable sense. * The situation is really complicated in general:

Jungle of topological manifolds:

* For $\dim M \leq 3 \exists!$ differentiable structure (Munkres, Maise)

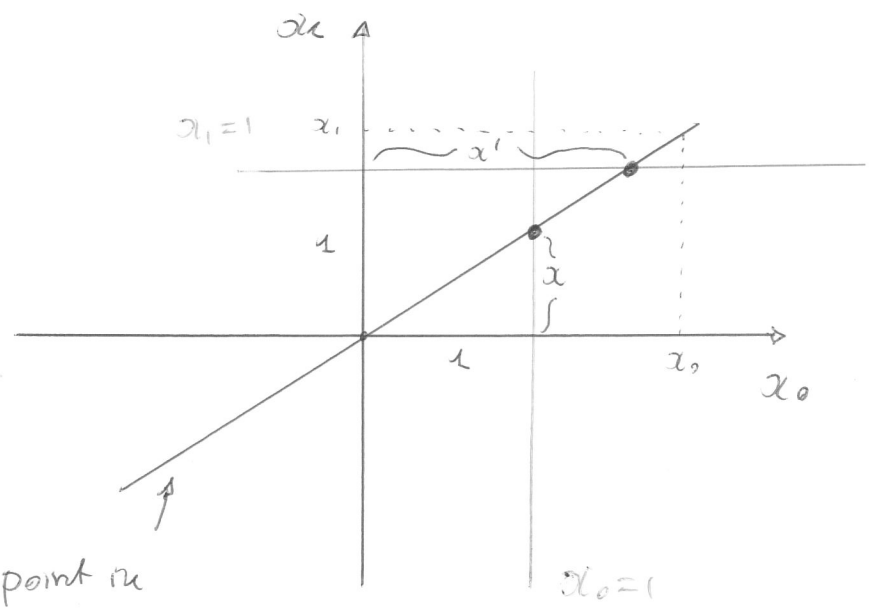
* In dimension > 3 , $\exists M$ which do not admit any differentiable structure.

* Exotic spheres (Milnor, Kuwartz): on S^7 there exist 28 inequivalent differentiable structures

* Fake \mathbb{R}^4 : on \mathbb{R}^4 , there exists an uncountable set of inequivalent differentiable structures (Freedman)

We refrain from further delving into these fascinating topics.

4. The real projective line $\mathbb{R}P^1(\mathbb{R})$: lines in \mathbb{R}^2 passing through the origin



a point in $\mathbb{R}P^1(\mathbb{R})$

inhomogeneous (affine) coordinate

$$\mathcal{U}_0 \ni [\overset{\neq 0}{x_0}, x_1] \xrightarrow{g_0} \left(1, \frac{x_1}{x_0} \right) \equiv \alpha$$

removed

$$\mathcal{U}_1 \ni [x_0, \overset{\neq 0}{x_1}] \xrightarrow{g_1} \left(\frac{x_0}{x_1}, 1 \right) \equiv \alpha'$$

in $\mathcal{U}_0 \cap \mathcal{U}_1$, $x_0 \neq 0, x_1 \neq 0$

$$\alpha \xrightarrow{g_1 \circ g_0^{-1}} \alpha' = \frac{1}{\alpha}$$

$$\alpha' = \frac{1}{\alpha}$$

Smooth with smooth inverse

5. Projective spaces (real & complex)

$$\mathbb{P}^n(\mathbb{R}) \equiv \mathbb{P}(\mathbb{R}^{n+1})$$

$$\mathbb{C} \qquad \mathbb{C}^{n+1}$$

$$\varphi_i([x_0 \dots x_n]) = \left(\frac{x_0}{x_i}, \dots, \overset{1}{\frac{x_i}{x_i}}, \dots, \frac{x_n}{x_i} \right) \in \begin{matrix} \mathbb{R}^n \\ \mathbb{C}^n \end{matrix}$$

↓ homogeneous coordinates
↓ " " " " " "
↓ 1
↑ omitted

defined on

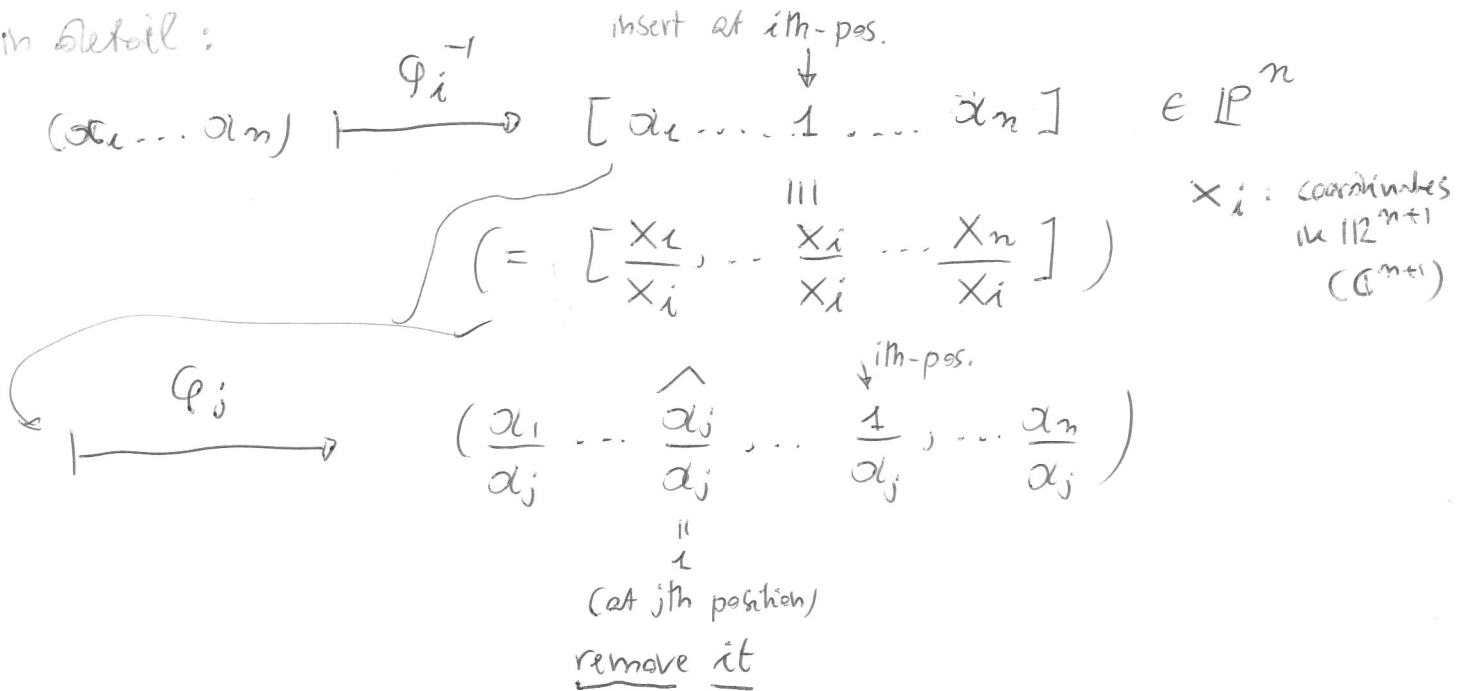
$$U_i = \{ [x] , x_i \neq 0 \}$$

let us calculate the transition maps, for $U_i \cap U_j \neq \emptyset$
 (i.e. $x_i \neq 0, x_j \neq 0$)

$$\varphi_j \circ \varphi_i^{-1}(x_1 \dots x_n) = \left(\frac{x_1}{x_j} \dots \frac{x_j}{x_j} , \frac{1}{x_j}, \dots, \frac{x_n}{x_j} \right)$$

jth position ith-position
1 ↓
= 1, omitted

in detail:

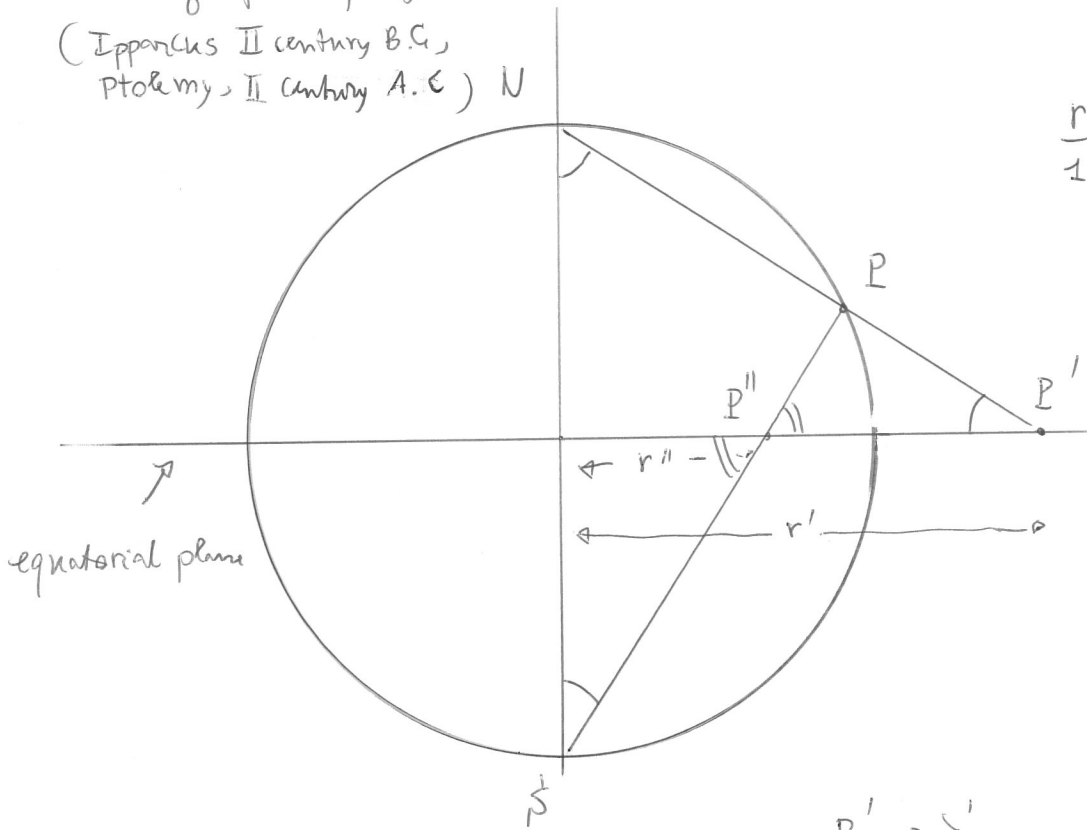


These maps are smooth (and holomorphic in the complex case)

5'. The Riemann sphere (the complex projective line as a Riemann surface)

stereographic projections

(Ipparchus II century B.C., Ptolemy, II century A.C.) N



$$\frac{r'}{1} = \frac{1}{r''}$$

$$r' = \frac{1}{r''}$$

$$P' \leftrightarrow \zeta' \quad r' = |\zeta'|$$

$$P'' \leftrightarrow \zeta'' \quad r'' = |\zeta''|$$

$$U_N = S^2 - \{N\}$$



$$U_S = S^2 - \{S\}$$



$$S^2 = U_N \cup U_S$$

$$\varphi_N: P \mapsto P'$$

$$\varphi_S: P \mapsto P''$$

If $P \notin \{N, S\}$ they are both defined

$$\varphi_N \circ \varphi_S^{-1}: P'' \xrightarrow{\varphi_S^{-1}} P \xrightarrow{\varphi_N} P'$$

equatorial plane

$$\zeta'' \mapsto \zeta'$$

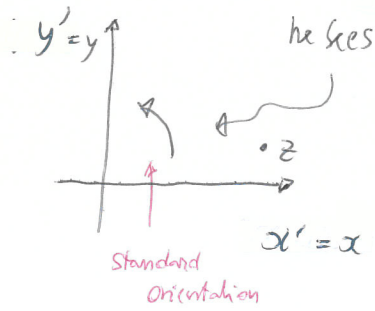
$$\begin{cases} x' = \frac{x''}{x''^2 + y''^2} \\ y' = \frac{-y''}{x''^2 + y''^2} \end{cases}$$

$$\zeta' = \frac{1}{\zeta''}$$

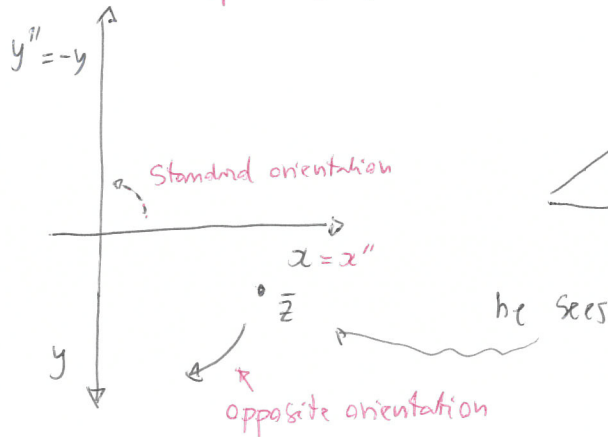
for suitable orientations (see further on)

Remark on orientation

take two copies of the equatorial plane $\cong \mathbb{C}$



* conjugation is involved

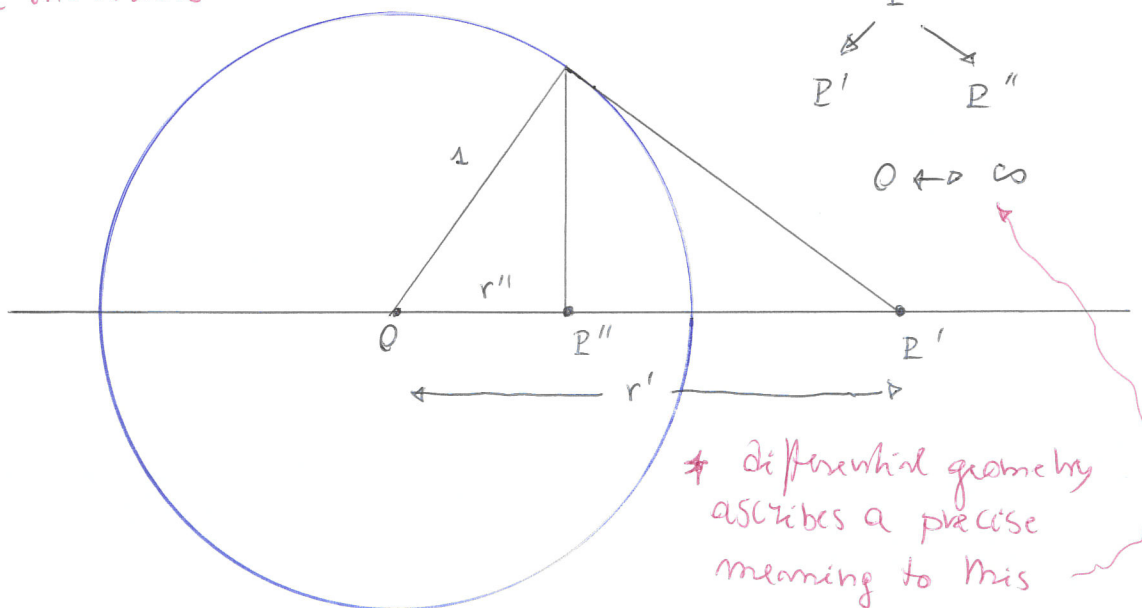


notice this

$$\underbrace{x'' + iy''}_{z''} = \frac{1}{\underbrace{x' + iy'}_{z'}} = \frac{x' - iy'}{x'^2 + y'^2}$$

Further remark: P' and P'' are related by a circular inversion

$$r' \cdot r'' = 1$$

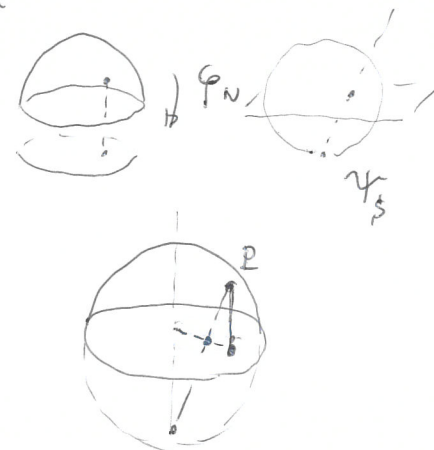
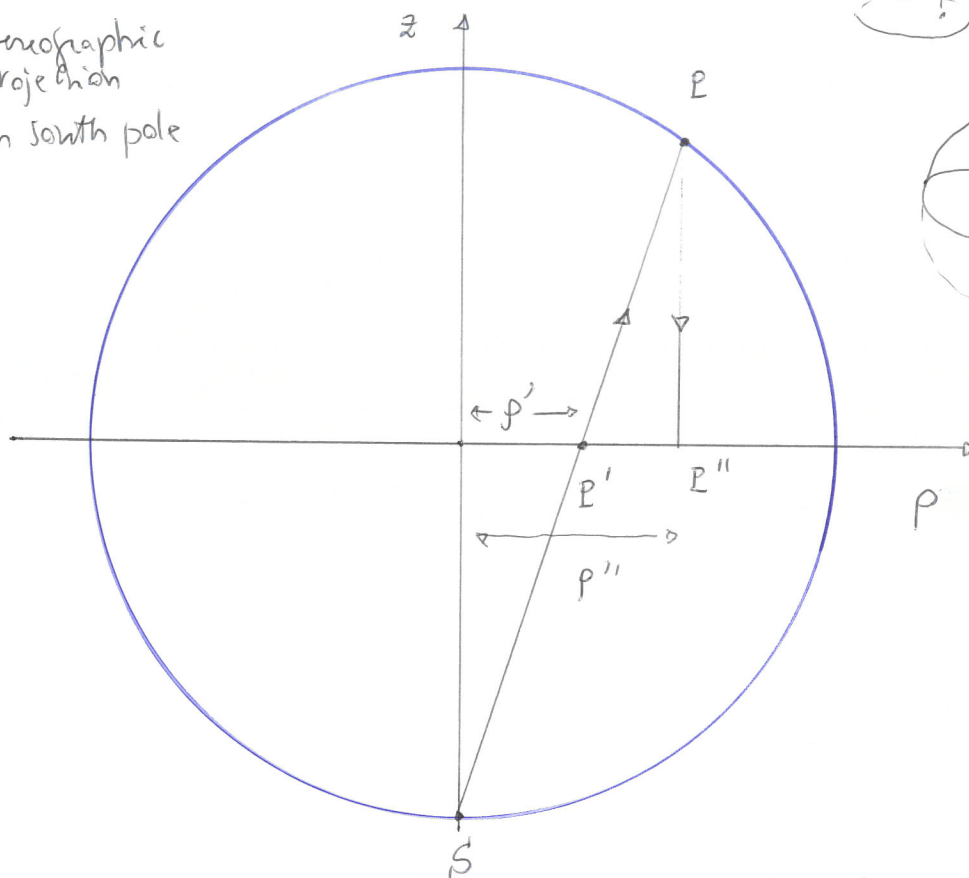


* differential geometry ascribes a precise meaning to this

6. Notice that we exhibited *two atlases* for the sphere. Let us check that they are compatible; it is then enough to show that the two charts below are compatible

$\varphi_N: U_N \rightarrow \mathbb{R}^2$ considered previously

ψ_S : stereographic projection from south pole



This is geometrically clear. Find the relationship between p' and p''

They define the same differentiable structure