

Lectures on: **DIFFERENTIAL GEOMETRY AND TOPOLOGY** V2

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Lecture XVII MAPS BETWEEN MANIFOLDS

- Smooth maps between manifolds
- differential
- example
- Tangent & cotangent bundles

★ Smooth maps between manifolds

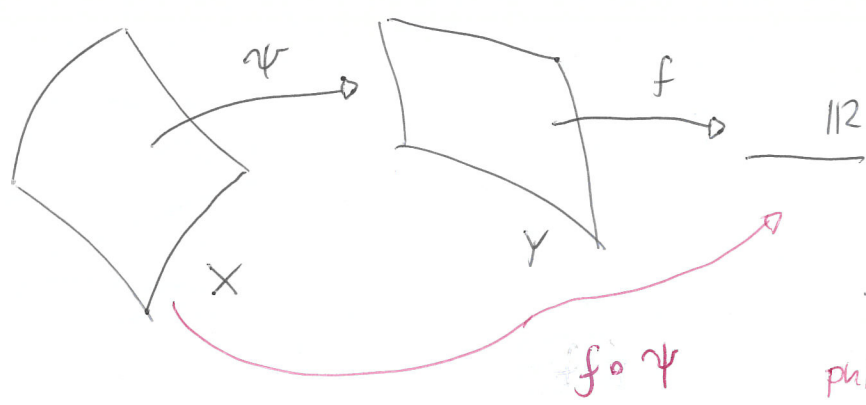
Let X, Y be differentiable manifolds of dimension n and m respectively

- Tensor bundles
- Riemannian metrics
- Behaviour under smooth maps

★ A map $\psi: X \rightarrow Y$ is said to be **Smooth**

if, whenever $f \in C^0(Y, \mathbb{R})$ smooth function on Y , then $f \circ \psi \in C^0(X, \mathbb{R})$

"Smooth is who smooth does"



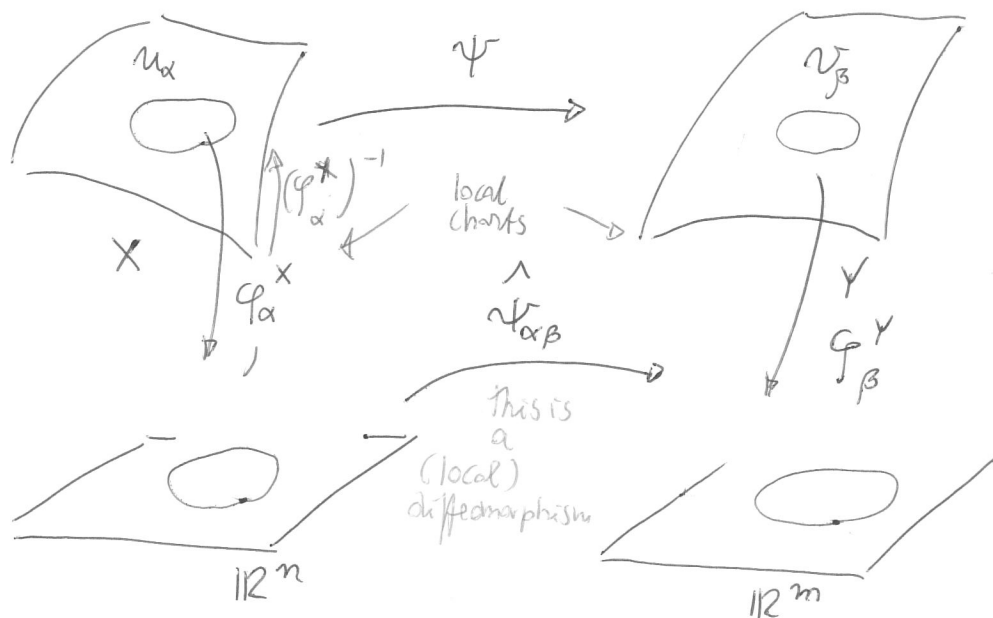
$f \circ \psi =: \psi^* f$
pull-back of f via ψ

"Knowing functions on X one knows X "

Def. $\psi: X \rightarrow Y$ is said to be a **(Smooth) diffeomorphism**

- if
- ψ is bijective (and smooth)
 - ψ^{-1} is smooth

Locally, $\psi: X \rightarrow Y$ induces smooth maps from \mathbb{R}^n to \mathbb{R}^m (upon applying the definition to local coordinate functions)



$$\psi_{\alpha\beta}^1 = \varphi_{\beta}^Y \circ \psi \circ (\varphi_{\alpha}^X)^{-1}$$

if ψ is smooth, and $f \in C^0(Y, \mathbb{R})$, then $f \circ \psi = \psi^* f \in C^0(X, \mathbb{R})$ by definition

* Differential of a smooth map.

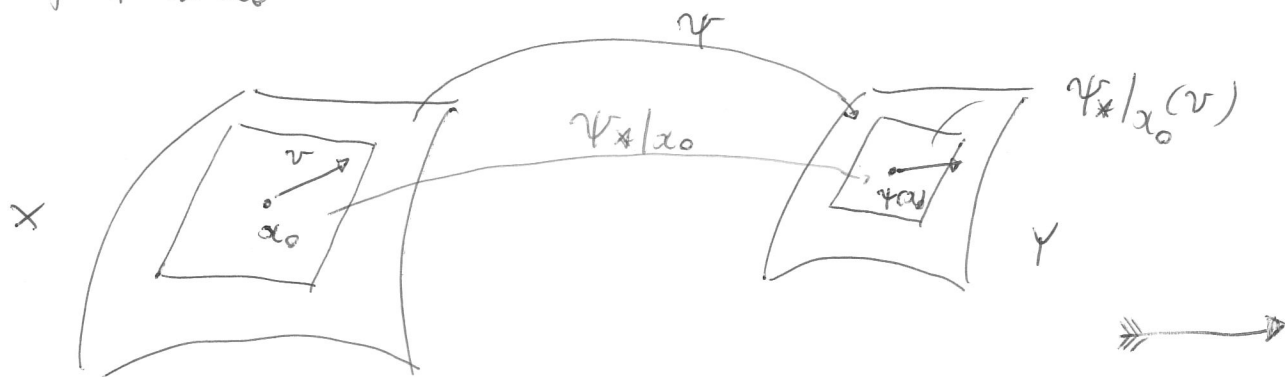
Let $\psi: X \rightarrow Y$ Smooth

and $\alpha_0 \in X$. One can define

$$d\psi|_{\alpha_0} \equiv \psi_*|_{\alpha_0}: T_{\alpha_0} X \rightarrow T_{\psi(\alpha_0)} Y$$

differential (push-forward) of ψ at α_0

$$\begin{array}{ccc} \psi & & \\ \downarrow & \longrightarrow & \psi_*|_{\alpha_0}(v) \\ v & & \end{array}$$

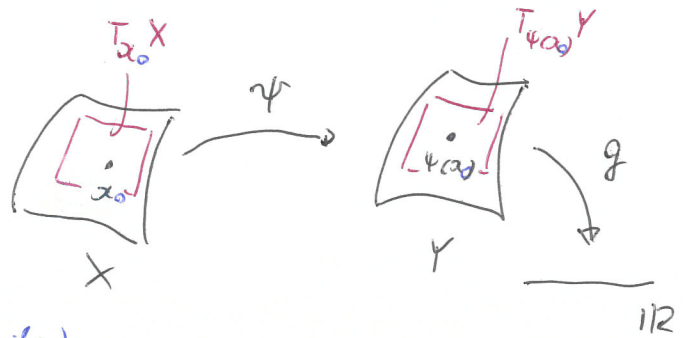


via the position

$$\left(\psi_* |_{\alpha_0} (v) \right) (g) := v (g \circ \psi)$$

\uparrow \uparrow \uparrow
 $T_{\alpha_0} X$ $C^\infty(Y, \psi(\alpha_0), \mathbb{R})$ $C^0(X, \alpha_0, \mathbb{R})$

This is a derivation, acting on functions defined on a neighbourhood of $\psi(\alpha_0)$



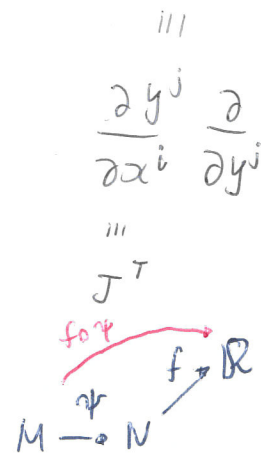
One finds that (See below for details)

$$\left(\psi_* |_{\alpha_0} (v) \right) (g) = \sum_{j=1}^m \left[v (y^j \circ \psi) \frac{\partial}{\partial y^j} \right] (g)$$

In particular $\psi_* |_{\alpha_0} \left(\frac{\partial}{\partial x^i} \right) = \sum_{j=1}^m \frac{\partial (y^j \circ \psi)}{\partial x^i} \frac{\partial}{\partial y^j}$

$$\frac{\partial}{\partial x^i} \longmapsto \frac{\partial y^j}{\partial x^i} \frac{\partial}{\partial y^j}$$

$$\frac{\partial}{\partial x} \longmapsto J^T \frac{\partial}{\partial y}$$



A more compact notation:

$$\left(\psi_* X \right) (f) (\psi(\alpha_0)) = X (f \circ \psi) (\alpha_0)$$

\uparrow \uparrow \uparrow \uparrow
 $T_{\psi(\alpha_0)} N$ N $T_{\alpha_0} N$ M



In general, vector fields are not mapped to vector fields
See below

★ Behaviour of vector fields and differential forms under smooth maps

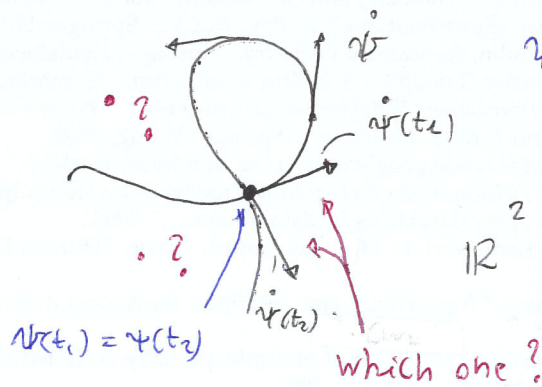
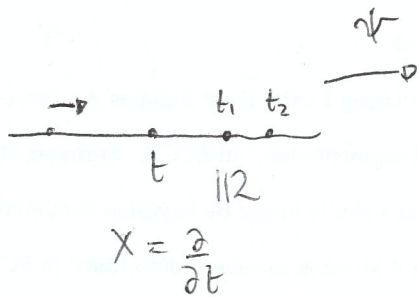
★ $\mathcal{X}(M)$ | Notice that in general, the push-forward of $\psi: M \rightarrow N$

$\psi_*: TM \rightarrow TN$

does NOT map vector fields on M to vector fields on N , in general. (Although, of course, ψ_* sends tangent vectors to M to tangent vectors to N)



Example



No problem arises if ψ is a diffeomorphism:

$$(\psi_* X)(f)(y) = X(\psi^* f)(x) = X(\psi^* f)(\psi^{-1}(y))$$

$\wedge \quad \uparrow \quad \wedge \quad \uparrow$
 $\mathcal{E}^0(N) \quad N \quad \mathcal{E}^0(M) \quad M$

$x = \psi^{-1}(y)$

★ $\Delta^k(M)$ | On the other hand, given $\omega \in \Delta^k(N)$, the pulled-back form $\psi^* \omega \in \Delta^k(M)$ is always defined (for any ψ smooth). One has:

$$(\psi^* \omega)(x)(X_1, \dots, X_k) = \omega(\psi(x))(\psi_* X_1, \dots, \psi_* X_k)$$

$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow$
 $T_x M \quad T_{\psi(x)} N$

(This definition extends the one given in the \mathbb{R}^n -case)

$$\psi: X \rightarrow Y$$

Let us provide some details

φ : coordinate system $(\alpha^1 \dots \alpha^n)$ around $x_0 \in X$
local chart

τ : $=$ $(y^1 \dots y^m)$ around $y_0 \in Y$

Compute:

$$(\psi_* |_{\alpha_0})(v) = v(g \circ \psi) = \sum_{i=1}^n a^i \frac{\partial}{\partial \alpha^i} (g \circ \psi)$$

$$= \sum_{i=1}^n a^i \frac{\partial}{\partial r^i} (g \circ \tau^{-1} \circ \tau \circ \psi \circ \varphi^{-1}) \Big|_{\varphi(x_0)}$$

Chain rule

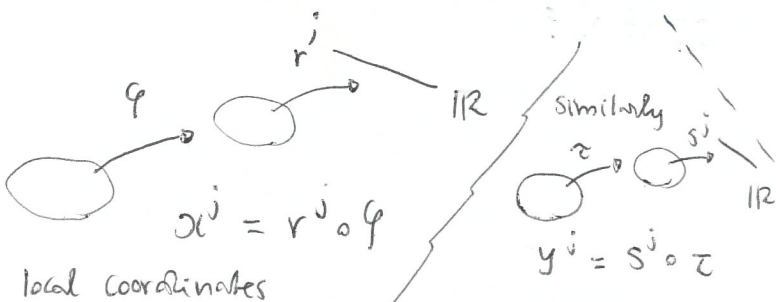
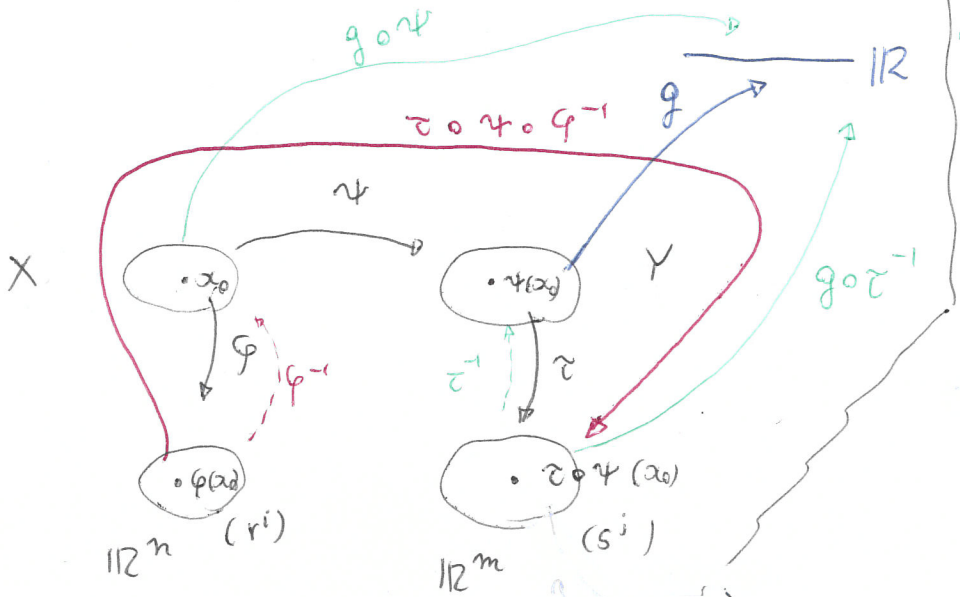
$$= \sum_{i=1}^n a^i \sum_{j=1}^m \frac{\partial}{\partial s^j} (g \circ \tau^{-1}) \Big|_{\tau \circ \psi(x_0)} \cdot \frac{\partial}{\partial r^i} (s^j \circ \tau \circ \psi \circ \varphi^{-1}) \Big|_{\varphi(x_0)}$$

Coordinate maps on \mathbb{R}^m

$$= \sum_{i=1}^n \sum_{j=1}^m a^i \frac{\partial g}{\partial y^j} \cdot \frac{\partial}{\partial \alpha^i} (y^j \circ \psi)$$

$$= \left[\sum_{j=1}^m v(y^j \circ \psi) \frac{\partial}{\partial y^j} \right] (g)$$

this is indeed a tangent vector at $\psi(x_0)$

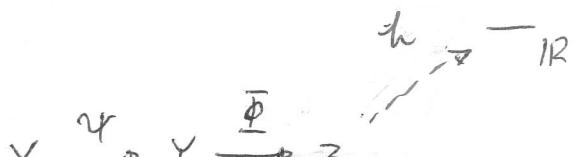


We find, in particular

$$\psi_* \Big|_{\alpha_0} : T_{\alpha_0} X \longrightarrow T_{\psi(\alpha_0)} Y$$

$$\frac{\partial}{\partial x^i} \longmapsto \sum_{j=1}^m \underbrace{\frac{\partial (y_j \circ \psi)}{\partial x^i}}_{(\psi_*|_{\alpha})_{ji}} \frac{\partial}{\partial y_j}$$

$\leftarrow J^T$

Let us also check that if $X \xrightarrow{\psi} Y \xrightarrow{\Phi} Z$ 

Then $d(\Phi \circ \psi) = d\Phi \circ d\psi$ generalized chain rule

\leftarrow as homeomorphisms matrix product.

$$\boxed{(\Phi \circ \psi)_* = \Phi_* \circ \psi_*}$$

associativity of \circ

$$\left[(\Phi \circ \psi)_*(v) \right] (h) \stackrel{\text{def}}{=} \psi(h \circ (\Phi \circ \psi)) = \psi((h \circ \Phi) \circ \psi)$$

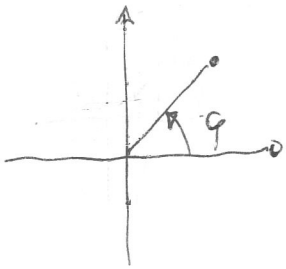
$$= \psi_*(v) (h \circ \Phi) = \Phi_*(\psi_*(v)) (h)$$

$$= \left[(\Phi_* \circ \psi_*)(v) \right] (h) \quad \square$$

* Example. Let $M = \mathbb{R}^2 - \{(x, 0) \mid x \geq 0\}$

$$\psi: \begin{matrix} M \subset \mathbb{R}^2 \\ (p, \varphi) \longmapsto (x, y) \in \mathbb{R}^2 \\ p > 0 \\ \varphi \in (0, 2\pi) \end{matrix} \quad \psi: \begin{cases} x = p \cos \varphi \\ y = p \sin \varphi \end{cases}$$

$$d\psi: \begin{cases} dx = dp \cos \varphi - p \sin \varphi d\varphi \\ dy = dp \sin \varphi + p \cos \varphi d\varphi \end{cases}$$



$$\psi_* \begin{pmatrix} \cos \varphi & -p \sin \varphi \\ \sin \varphi & p \cos \varphi \end{pmatrix}$$

$$\frac{\partial}{\partial p} \mapsto \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\frac{\partial}{\partial \varphi} \mapsto \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\psi_* \left(\frac{\partial}{\partial p} \right) = \cos \varphi \frac{\partial}{\partial x} + \sin \varphi \frac{\partial}{\partial y} = \frac{x}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial x} + \frac{y}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial y}$$

$$\psi_* \left(\frac{\partial}{\partial \varphi} \right) = -p \sin \varphi \frac{\partial}{\partial x} + p \cos \varphi \frac{\partial}{\partial y} = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}$$

This is of course in agreement with the general definition

$$\boxed{(\psi_* X)(f) = X(f \circ \psi)}$$

Take $X = \frac{\partial}{\partial p}$. Compute:

$$\psi_* \left(\frac{\partial}{\partial p} \right) (f) = \frac{\partial}{\partial p} (f \circ \psi) = \frac{\partial f}{\partial x} \frac{\partial x}{\partial p} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial p}$$

" $f = f(x, y)$ "

" $f = f(p, \varphi)$ "

$$= \frac{\partial f}{\partial x} \cos \varphi + \frac{\partial f}{\partial y} \sin \varphi \Rightarrow \boxed{\psi_* \left(\frac{\partial}{\partial p} \right) = \frac{x}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial x} + \frac{y}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial y}} \quad \checkmark$$

"remove f"

Similarly:

$$\psi_* \left(\frac{\partial}{\partial p} \right) (f) = \frac{\partial}{\partial q} (f \circ \psi) = \frac{\partial f}{\partial x} \frac{\partial x}{\partial q} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial q}$$

$$= \frac{\partial f}{\partial x} \underbrace{(-p \sin \varphi)}_{-y} + \frac{\partial f}{\partial y} \underbrace{(p \cos \varphi)}_x \Rightarrow \boxed{\psi_* \left(\frac{\partial}{\partial q} \right) = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}}$$

Let us examine this "classical" computation as well (useful in general)

$$\frac{\partial f}{\partial p} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial p} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial p}$$

$$\frac{\partial f}{\partial q} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial q} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial q}$$

$$\begin{pmatrix} \frac{\partial x}{\partial p} & \frac{\partial y}{\partial p} \\ \frac{\partial x}{\partial q} & \frac{\partial y}{\partial q} \end{pmatrix} = J^t$$

that is:
(remove f)

$$\begin{pmatrix} \frac{\partial}{\partial p} \\ \frac{\partial}{\partial q} \end{pmatrix} = \begin{pmatrix} \cos \varphi & \sin \varphi \\ -p \sin \varphi & p \cos \varphi \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix}$$

$$\begin{cases} \frac{\partial}{\partial p} = \frac{x}{r} \frac{\partial}{\partial x} + \frac{y}{r} \frac{\partial}{\partial y} \\ \frac{\partial}{\partial q} = \underbrace{-p \sin \varphi}_{-y} \frac{\partial}{\partial x} + \underbrace{p \cos \varphi}_x \frac{\partial}{\partial y} \end{cases}$$

but this is
to be interpreted
as \diamond & $\diamond\diamond$
 $\frac{\partial}{\partial p}$ is actually $\psi_* \left(\frac{\partial}{\partial p} \right)$
and similarly for $\frac{\partial}{\partial q}$!