

Lectures on DIFFERENTIAL GEOMETRY AND TOPOLOGY V2

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Lecture XXIV

★ On the Frobenius Theorem

FROBENIUS' THEORY

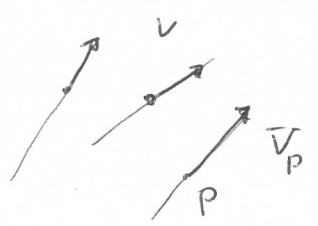
• distributions
& their integrability

Prelude: Working in \mathbb{R}^2 , for simplicity, the problem

$$\begin{cases} \dot{x} = X \\ \dot{y} = Y \end{cases} \quad V = (X, Y) \text{ vector field}$$

consists on the following:

Given a direction field, determined, pointwise, by a vector field V (one has $\langle V_p \rangle \subseteq \mathbb{R}^2$)



↑
Subspace

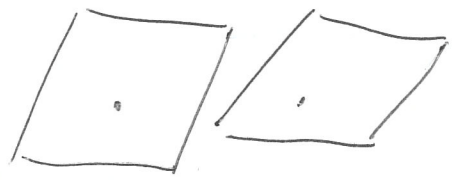
find its integral curves, i.e. curves such

that whose tangents at each point have the given direction.

The Cauchy-Lipschitz Theorem asserts that, at least locally, the problem admits a (unique) solution.

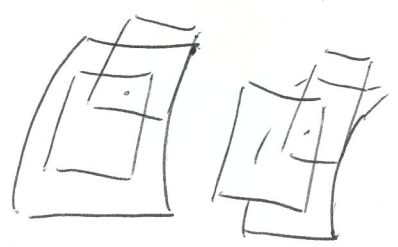


Let us generalize. Work for instance in \mathbb{R}^3 , and assign a distribution of planes $p \mapsto \Delta_p$ in \mathbb{R}^3



Does there exist, $\forall p$, an integral manifold of the above distribution,

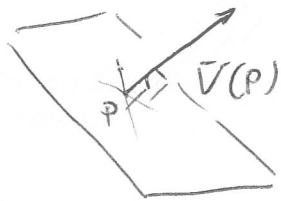
namely, a surface Σ_p such that $T_p \Sigma_p = \Delta_p \forall p$?



[in order to identify Δ_p , let us assign a pair of vector fields (X_1, X_2) such that, locally $(X_1(q), X_2(q))$ yield a basis of Δ_q :

$$\text{span}(X_1(q), X_2(q)) = \Delta_q$$

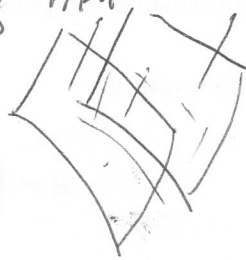
To be concrete, let $V \in \mathcal{X}(\mathbb{R}^3)$ be a vector field. Consider, at each point $p \in \mathbb{R}^3$, the plane π_p through p perpendicular to $V(p)$.



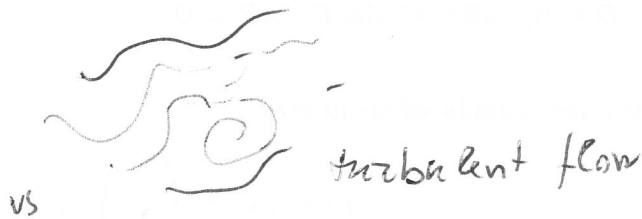
One obtains a distribution of planes. We are going to discuss a necessary and sufficient condition ensuring that

$$\pi_p = T_p \Sigma_p$$

↑
surface

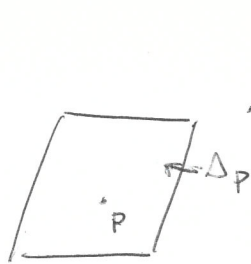


In fluid mechanics, this is the issue of laminarity



The answer is NO, in general

Let us formalize the preceding discussion



Let \$M\$ be a smooth manifold,

$$\dim M = n + 1$$

For all \$p \in M\$, let \$\Delta_p \subseteq T_p M\$,
 $\dim \Delta_p = n$. Consider the map

$$\Delta: M \ni p \longmapsto \Delta_p \subseteq T_p M$$

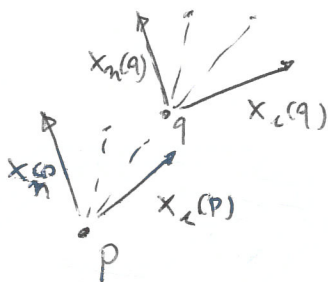
Assume that \$\forall p \in M\$, \$\exists U \ni p\$ and \$x_1, \dots, x_n \in \mathcal{X}(U)\$

such that, \$\forall q \in U\$, \$(x_1(q) \dots x_n(q))\$ provide a basis for \$\Delta_q\$.

\$\Delta\$ is then termed Smooth
distribution of dimension \$n\$

(smooth \$n\$-dimensional distribution)

and \$(x_1 \dots x_n)\$ gives a local basis thereof.



Def. \$\Delta\$ is called involutive if, in a suitable neighbourhood of each point, there exists a local basis \$(x_1, \dots, x_n)\$ of \$\Delta\$ such that, for suitable \$C_{ij}^k \in \mathcal{C}^\infty(M)\$,

one has

$$\boxed{[X_i, X_j] = C_{ij}^k X_k} \quad \leftarrow \text{Einstein}$$

Lie bracket

↑
functions

i.e. \$\Delta\$ is closed (locally) with respect to the Lie bracket of vector fields.

Remark The above concept is basis-independent, i.e.

given a local basis (X_1, \dots, X_n) for Δ with the property

$$[X_i, X_j] = C_{ij}^k X_k \quad (*)$$

||| (i.e. Δ is involutive), then the same holds for any other local basis:

Let $Y_i = \beta_i^j X_j$; then

$$[Y_i, Y_j] = [\beta_i^l X_l, \beta_j^h X_h] =$$

$$\beta_i^l X_l (\beta_j^h X_h) - \beta_j^h X_h (\beta_i^l X_l) =$$

$$= \beta_i^l X_l (\beta_j^h) X_h - \beta_j^h X_h (\beta_i^l) X_l$$

$$+ \beta_i^l \beta_j^h [X_h, X_l] = \quad (\text{use } (*))$$

$$= \beta_i^l X_l (\beta_j^h) X_h - \beta_j^h X_h (\beta_i^l) X_l$$

$$+ \beta_i^l \beta_j^h C_{hl}^p X_p = \underset{\substack{\uparrow \\ \text{function} \\ \text{coefficients}}}{d_{ij}^k} (X_1, \dots, X_n)$$

(Y_i) is a local basis

$$= d_{ij}^k (Y_1, \dots, Y_n)$$

$$\text{i.e.} \quad [Y_i, Y_j] = d_{ij}^k Y_k$$

for suitable smooth functions d_{ij}^k

Typical example : in \mathbb{R}^m

$$m = n + k$$

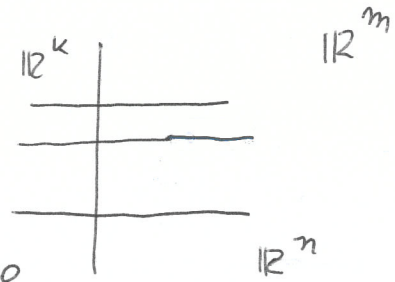
$$\Delta = \left\langle \frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n} \right\rangle$$

Notice that in this case

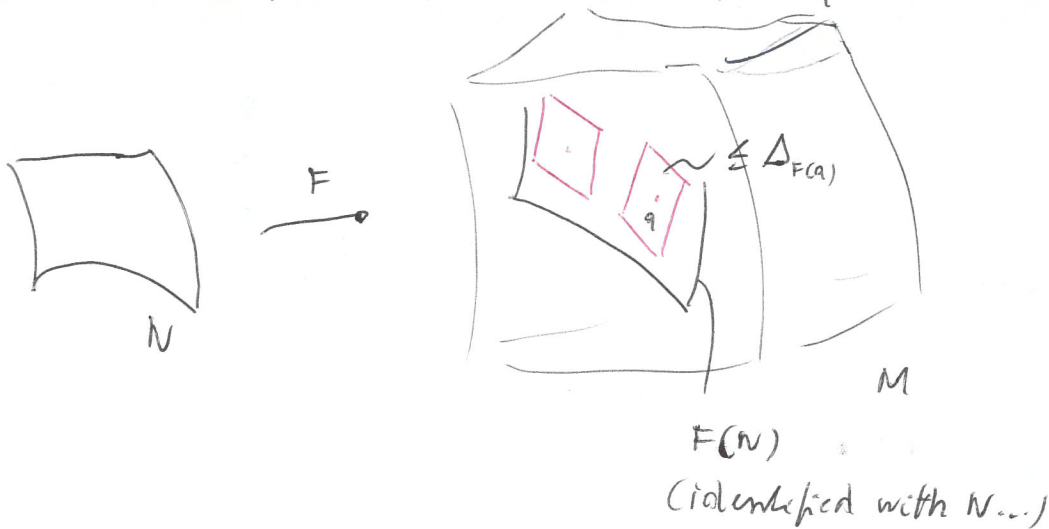
$$c_{ij}^{1k} \equiv 0$$

$$\left[\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right] = 0$$

The $\frac{\partial}{\partial x^i}$ commute



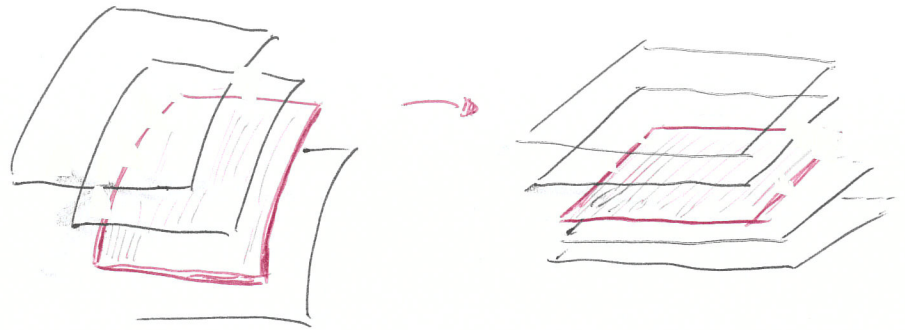
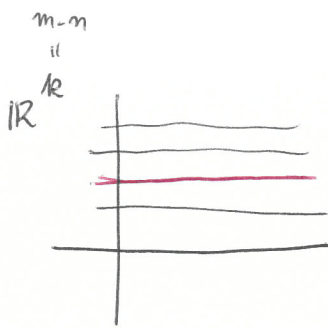
Def. (i) An integral submanifold of Δ is a manifold N such that, if $F: N \rightarrow M$ is an injective immersion, one has, $\forall q \in N$, $F_*(T_q(N)) \subseteq \Delta_{F(q)}$



(ii) Δ is called completely integrable if, $\forall p \in M$, \exists a local coordinate system (defined on $U \ni p$)

$\left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n} \right)$ giving a local basis for Δ .

This being the case, there exists N integral submanifold where $T_q N = \Delta_q \quad \forall q \in U$,
defined by $\{ x^i = a^i, i = n+1, \dots, m \}$
i.e. N is an n -slice of U



Notice that Δ is clearly involutive.

The basic result governing the theory is the following:

*** Theorem (Frobenius) Δ is involutive if and only if it is completely integrable

Comment: (\Leftarrow) is clear in view of the preceding discussion

Also notice that if $N \subset M$ is a submanifold of M , $\mathcal{F}(N)$ is a lie algebra. So the condition is necessary.

The crucial point is to prove sufficiency, which can be ascertained by induction and using the fact that an involutive distribution can be generated pointwise by commuting vector fields.

see chapter on symplectic geometry

*** Application The Liouville - Arnold's Theorem in mechanics.

Given a Hamiltonian system (M, ω, H) $\dim M = 2n$

$\{f_i\}_{i=1, \dots, n}$ first integrals in involution ($\{f_i, f_j\} = 0$

($\Rightarrow [X_{f_i}, X_{f_j}] = 0$) which are

also functionally independent, the X_{f_i} yield a

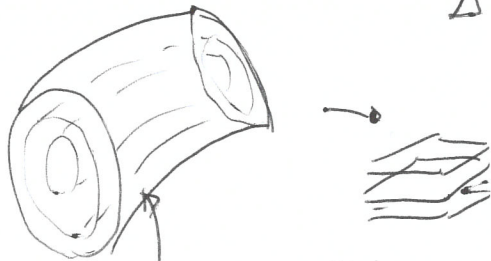
completely integrable distribution, whose integral submanifolds, under suitable conditions, are tori (Liouville or Lagrangian tori)

one can find local action-angle variables

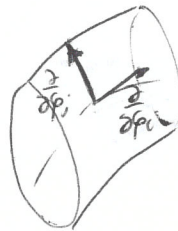
$N \sim$
 $(\varphi_1, \dots, \varphi_n, I_1, \dots, I_n)$
 angles actions

$$\omega = d\varphi \wedge dI \quad (= \sum d\varphi_i \wedge dI_i)$$

$$\Delta = \left\{ \frac{\partial}{\partial \varphi_i} \right\}_{i=1, \dots, n}$$



torus labelled by I , with angle coordinates on it (Lagrangian, or Liouville torus)



Hamilton's equations become:

and are indeed immediately integrated \rightarrow

$$\left\{ \begin{array}{l} \dot{I}_i = 0 \Rightarrow I_i = \text{constant} \\ \dot{\varphi}_i = c_i \quad (\text{constant}) \end{array} \right.$$

$$\varphi_i = \varphi_i^0 + t c_i$$

linearization of the flow

Example: The harmonic oscillator.



The trajectory winds on a fixed

Lagrangian (or Liouville)
torus

"quasiperiodicity"

Another very important example

See Chapter on Lie groups

Let G be a Lie group, with Lie algebra \mathfrak{g}

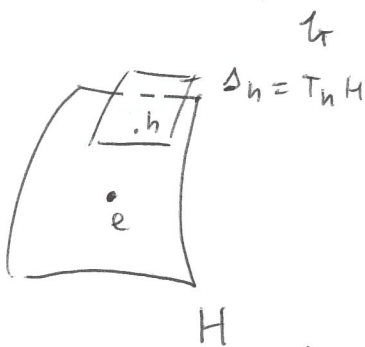
H a Lie subgroup of G , with Lie algebra \mathfrak{h}
 (it is enough to require H closed, then it will be automatically a Lie group)

$\mathfrak{h} = \left\{ \begin{array}{l} \text{left invariant vector fields on } G \\ \text{and tangent to } H \text{ in } e \end{array} \right\}$
 \uparrow
 neutral element

\mathfrak{h} is a Lie subalgebra of \mathfrak{g}

So there exists Δ , distribution on G such that $\Delta_h = T_h H$ and, in general,

$$\Delta_g = T_g(gH)$$



By Frobenius' theorem, Δ is completely integrable and its integral submanifolds are precisely

the cosets $gH = \{ gh \mid h \in H, g \in G \text{ fixed} \}$
 characteristic



Note: if H is closed, gH is an embedded submanifold of G and the quotient space G/H will be a manifold as well.