

Lectures on DIFFERENTIAL GEOMETRY AND TOPOLOGY

v2

Prof. Marco Spica - Dipartimento di Matematica e Fisica
"Niccolò Tartaglia" - UCSC Brescia

Lecture XXXIX

INTEGRATION

◇ Integration on manifolds

★ Integration on \mathbb{R}^n

In \mathbb{R}^n , if $f \in C_c^\infty(\mathbb{R}^n)$, one defines the ordinary
compact support

Riemann integral

$$\int_{\mathbb{R}^n} f \, dx_1 \dots dx_n$$

If $\omega = f \, dx_1 \wedge dx_2 \wedge \dots \wedge dx_n \in \Lambda_c^n(\mathbb{R}^n)$

(an n -form with compact support), one sets:

$$\int_{\mathbb{R}^n} \omega := \int_{\mathbb{R}^n} f \, dx_1 \dots dx_n$$

With this definition, one has, for $\omega' = f \, dx_{\pi(1)} \wedge \dots \wedge dx_{\pi(n)}$

$\pi \in S_n$ (a permutation),

$$\int_{\mathbb{R}^n} \omega' = \underbrace{(-1)^\pi}_{\substack{\text{sign, or parity} \\ \text{of } \pi}} \int_{\mathbb{R}^n} f \, dx_1 \wedge \dots \wedge dx_n = (-1)^\pi \int_{\mathbb{R}^n} \omega$$

Upon performing a coordinate change (diffeomorphism)

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$y \rightarrow x$$

$$x = Ty$$

$$x_i \equiv T_i(y_1, \dots, y_n)$$

$$\text{" } x_i \circ T(y_1, \dots, y_n)$$

one has

$$\frac{dx_1 \dots dx_n}{dT_1 \dots dT_n} = \det \left(\frac{\partial x_i}{\partial y_j} \right) dy_1 \dots dy_n$$

$$\underbrace{\hspace{10em}}_{\substack{J(T) \\ \text{Jacobian}}} \equiv J(T) dy_1 \dots dy_n$$

Hence

$$\int_{\mathbb{R}^n} T^* \omega \stackrel{\text{pull-back}}{=} \int_{\mathbb{R}^n} (f \circ T) dT_1 \dots dT_n$$

$$= \int_{\mathbb{R}^n} (f \circ T) J(T) dy_1 \dots dy_n$$

However, one also has

$$\int_{\mathbb{R}^n} \omega = \int_{\mathbb{R}^n} f(x_1, \dots, x_n) dx_1 \dots dx_n$$

$$= \int_{\mathbb{R}^n} f(x_1, \dots, x_n) dx_1 \dots dx_n$$

$$= \int_{\mathbb{R}^n} (f \circ T) |J(T)| dy_1 \dots dy_n$$

← notice this

whence

$$\boxed{\int_{\mathbb{R}^n} T^* \omega = \pm \int_{\mathbb{R}^n} \omega}$$

T is said to be orientation preserving if $J(T) > 0$

otherwise ($J(T) < 0$) T is called orientation reversing.

Recall that two bases b, b' in \mathbb{R}^n are called equioriented (or: yield the same orientation) if $\det m_{bb'}(I) > 0$
(change of basis)

We also write

$$T^* dx_1 \wedge \dots \wedge dx_n = J(T) dy_1 \wedge \dots \wedge dy_n$$

(upon changing names) $\equiv \int \alpha(x) dx_1 \wedge \dots \wedge dx_n$
 $\equiv J(T)$

$T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is then orientation preserving if and only if $\alpha > 0$.

* Orientable manifolds

Let M be a smooth manifold, $\mathcal{A} = \{ \mathcal{U}_\alpha, \varphi_\alpha \}_{\alpha \in \mathcal{A}}$ an atlas for M . \mathcal{A} is said to be oriented if the transition functions $\varphi_\alpha \circ \varphi_\beta^{-1}$ are orientation preserving. If M possesses an oriented atlas, then it is called orientable.

The following is important:

* Proposition A smooth manifold M , $\dim M = n$ is orientable if and only if there exists a never vanishing global n -form ω on M ($\omega \in \Lambda^n(M)$, $\omega \neq 0$ at every point).

Proof.

(\Leftarrow) Let ω be a global n -form, $\omega(x) \neq 0 \forall x \in M$.

Given a local chart φ_α , one has
 $\xrightarrow{\alpha_i: \text{local coordinates on } \mathbb{R}^n}$

$$\varphi_\alpha^* dx_1 \wedge \dots \wedge dx_n = f_\alpha \omega, \quad f_\alpha \neq 0 \text{ on } \mathcal{U}_\alpha$$

Similarly $\varphi_\beta^* dx_1 \wedge \dots \wedge dx_n = f_\beta \omega, \quad f_\beta \neq 0 \text{ on } \mathcal{U}_\beta$

One can arrange things (by a suitable switch of coordinates)

in such a way that $f_\alpha > 0 \quad \forall \alpha \in \mathcal{A}$

Then we have: $\omega = f_\alpha^{-1} \varphi_\alpha^* (dx_1 \wedge \dots \wedge dx_n) = f_\beta^{-1} \varphi_\beta^* (dx_1 \wedge \dots \wedge dx_n)$

$$\Rightarrow \varphi_\alpha^* (dx_1 \wedge \dots \wedge dx_n) = \underbrace{f_\alpha f_\beta^{-1}}_f \varphi_\beta^* (dx_1 \wedge \dots \wedge dx_n). \quad \text{Then}$$

$$\boxed{(\varphi_\beta^{-1})^* \varphi_\alpha^* (dx_1 \wedge \dots \wedge dx_n) = (\varphi_\beta^{-1})^* [f \varphi_\beta^* (dx_1 \wedge \dots \wedge dx_n)] = \text{(injectivity)}}$$

$$(\varphi_\beta^{-1})^* \underbrace{(\varphi_\beta^*)^{-1} \varphi_\beta^*}_{\text{identity}} (dx_1 \wedge \dots \wedge dx_n) = \underbrace{(f \circ \varphi_\beta^{-1})}_f(x) dx_1 \wedge \dots \wedge dx_n$$

which shows that \mathcal{A} is oriented. $f(x) > 0$

(\Rightarrow) Conversely, given \mathcal{A} oriented, we have:

$$(\varphi_\alpha \circ \varphi_\beta^{-1})^* dx_1 \wedge \dots \wedge dx_n = \underbrace{f}_f(x) dx_1 \wedge \dots \wedge dx_n$$

"

$$(\varphi_\beta^{-1})^* \varphi_\alpha^* dx_1 \wedge \dots \wedge dx_n$$

"

$$(\varphi_\beta^*)^{-1} \varphi_\alpha^* dx_1 \wedge \dots \wedge dx_n$$

\Rightarrow

$$\begin{aligned} & \varphi_\alpha^* (dx_1 \wedge \dots \wedge dx_n) \\ &= \varphi_\beta^* (f dx_1 \wedge \dots \wedge dx_n) \\ &= (\varphi_\beta \circ \varphi_\alpha)^* \underbrace{\varphi_\beta^* (dx_1 \wedge \dots \wedge dx_n)}_{\omega_\beta} \\ & \Rightarrow f > 0 \text{ on } \mathcal{U}_\alpha \cap \mathcal{U}_\beta \end{aligned}$$

That is

$$\boxed{\omega_\alpha = f \omega_\beta}$$

on $\mathcal{U}_\alpha \cap \mathcal{U}_\beta$,

and $\underline{f > 0}$ wherever

* Given a partition of unity $\{\rho_\alpha\}_{\alpha \in \mathcal{O}}$ subordinate to the covering $\{\mathcal{U}_\alpha\}_{\alpha \in \mathcal{O}}$, set

$$\boxed{\omega = \sum_{\alpha \in \mathcal{O}} \rho_\alpha \omega_\alpha}$$

Since $\rho_\alpha \geq 0$, $\sum \rho_\alpha \equiv 1$, it follows that

$\omega \neq 0$ everywhere. \square

If M is orientable (assume M connected as well)

Then, given ω, ω' non-vanishing n -forms on M , one has $\omega' = f \omega$, $f \neq 0$ everywhere

Actually $f \geq 0$.

Introduce the following equivalence relation on such forms: $\omega \sim \omega'$ if $\omega' = f \omega$, $f > 0$

Then $[\omega] = \{ \omega' \mid \omega' = f \omega, f > 0 \}$ (the class of ω)

Actually, one has exactly two equivalence classes:

each of these is called an orientation on M .

An oriented manifold is an orientable manifold M together with the choice of an orientation (notation: $[M]$)

Example: \mathbb{R}^n , with $[\omega = dx_1 \wedge \dots \wedge dx_n] = \left\{ \int dx_1 \wedge \dots \wedge dx_n, \int > 0 \right\}$
 is an oriented manifold (this is the standard orientation).

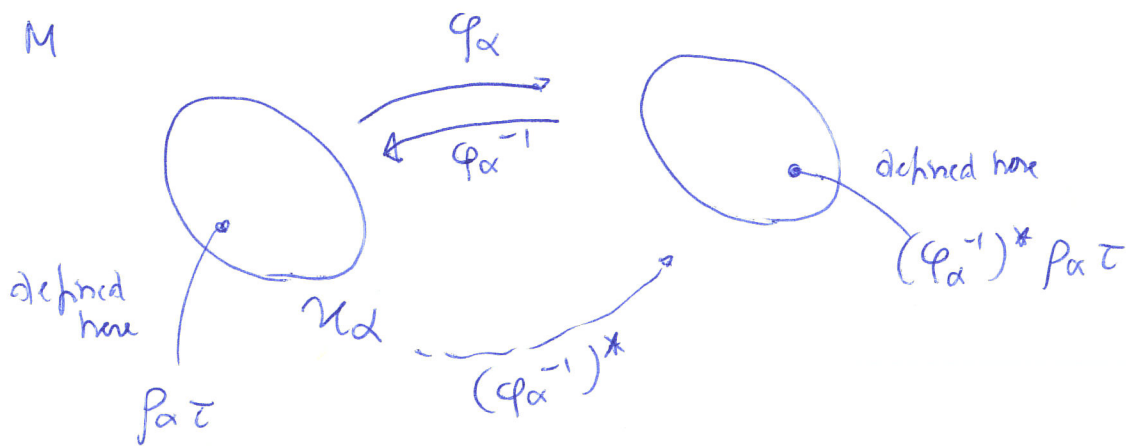
* Integration of n -forms on an oriented manifold

Now, consider an oriented manifold $[M]$
 (very often we shall discard $[]$).

Let $\tau \in \Lambda_c^n(M)$. Define

$$\int_{[M]} \tau := \sum_{\alpha \in \mathcal{A}} \int_{U_\alpha} p_\alpha \tau := \sum_{\alpha \in \mathcal{A}} \int_{\mathbb{R}^n} (\varphi_\alpha^{-1})^* p_\alpha \tau$$

(Of course $\mathcal{A} = \{U_\alpha, \varphi_\alpha\}_{\alpha \in \mathcal{A}}$ is an oriented atlas, and $\{p_\alpha\}_{\alpha \in \mathcal{A}}$ a partition of unity subordinate to $\{U_\alpha\}_{\alpha \in \mathcal{A}}$



(* $\int_{U_\alpha} p_\alpha \tau$ is well-defined, in view of orientability)

we write, for brevity

$$\int_M \tau \quad \text{instead of} \quad \int_{[M]} \tau$$

Of course, we have to check that $\int_M \tau$ is well-defined, i.e. it depends neither on \mathcal{A} (oriented atlas), nor on $\{P_\alpha\}$. This will be done presently.

First of all, observe that

$$\underbrace{\text{supp } P_\alpha \tau}_{\text{Closed}} \subseteq \text{supp } P_\alpha \cap \text{supp } \tau_\alpha \subseteq \underbrace{\text{supp } \tau}_{\text{Compact}}$$

But, in a Hausdorff space, K closed $\subseteq H$ compact $\Rightarrow K$ compact, so $P_\alpha \tau$ (and $(\varphi_\alpha^{-1})^* P_\alpha \tau$) has compact support.

Let $\mathcal{B} = \{V_\beta, \psi_\beta\}_{\beta \in B}$ be another oriented atlas (compatible with the former), and let $\{\chi_\beta\}_{\beta \in B}$ be an associated partition of unity. Then:

$$\boxed{\sum_\alpha \int_{U_\alpha} P_\alpha \tau = \sum_{\alpha, \beta} \int_{U_\alpha} P_\alpha \chi_\beta \tau} \quad (\text{since } \sum_\beta \chi_\beta = 1)$$

Now $\text{supp } P_\alpha \chi_\beta \subseteq U_\alpha \cap V_\beta$



\nwarrow may be empty

$$\Rightarrow \sum_{\alpha, \beta} \int_{U_\alpha} P_\alpha \chi_\beta \tau = \sum_{\alpha, \beta} \int_{V_\beta} P_\alpha \chi_\beta \tau$$

$$\stackrel{(\text{since } \sum_\alpha P_\alpha = 1)}{=} \boxed{\sum_\beta \int_{V_\beta} \chi_\beta \tau} \quad \square$$